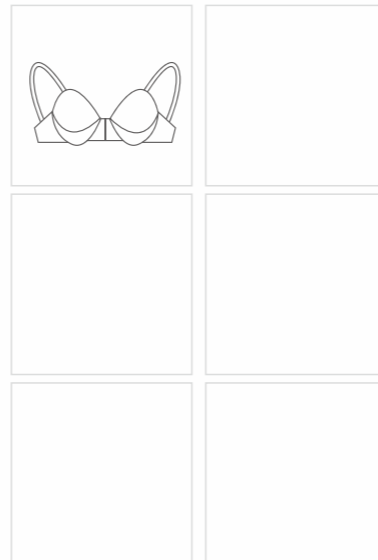
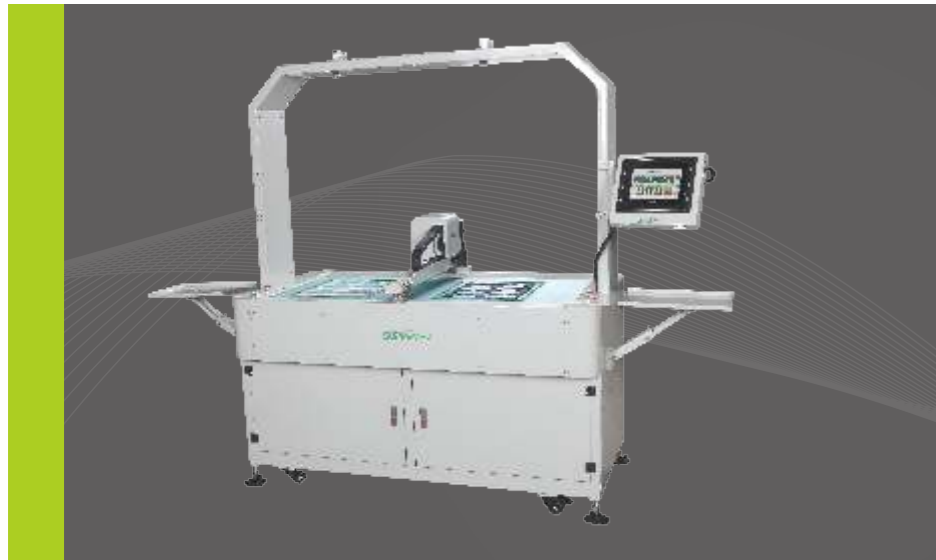


SP-F109



- 面料可随意摆放，通过视觉检测系统可准确定位。
- With visual position-hunting system. Part pieces could be put randomly.
- 拥有快捷的操作系统，完全可视化的人机界面。可直接编辑花样，并集合了数据的管理和可视化触摸操作特点。
- With visible human-machine interface and convenient operating system, it can program the patterns directly. The operation combined data management with visual touch screen.

自动定位超声波点焊机

Automatic Ultrasonic Welding Machine

采用先进的视觉识别、超声波焊接技术，定位精确，特别适合无缝内衣的热熔性材料、无纺布品、鞋类补墙等材料粘合。点位过程所有的频率、速度和压力由电脑程序控制。

With visual system, ultrasonic welding tech, accurate locating function. Used widely in under wear, shoes, no-woven material which are controlled by computer.

实例分析 Comparisons

作业方式 Working method	传统手工 Labour	自动点焊机 Machine
工序 Way	工作时间 Working time	工作时间 Working time
取待点位熔接面料置 放至工作台面 Feeding	1	1
点位熔接 (以一片面料16个点位计算) Welding tack	16	6 (与置放同步) Feeding while welding
至移转框 Into box	1	1
标准工时 Standard time	18	7
生产力 (件/人·小时) Production (P/M-H)	200	520
日产量提升 Daily Output(10 Hours)	2000	5200

日产量提升 Daily Production increased by

$$(5200-2000)/2000= 160\% \uparrow$$

